

Obtaining Electromagnetic and Muonic Signals

$$\begin{pmatrix} S_{\rm top} \\ S_{\rm bot} \end{pmatrix} = \mathcal{M} \begin{pmatrix} S_{\rm EM} \\ S_{\mu} \end{pmatrix} = \begin{pmatrix} a & b \\ 1-a & 1-b \end{pmatrix} \begin{pmatrix} S_{\rm EM} \\ S_{\mu} \end{pmatrix}$$

a + b \rightarrow from simulations, depend on detector specifics S_{top} + S_{bot} \rightarrow from calibrated PMT signals

<u>Analysis Goal:</u> Obtain calibrated S_{top} and S_{bot} Can then invert matrix to obtain S_{EM} and S_{μ}

Determination of Matrix Coefficients (a + b)



Prototype Detectors at the Pierre Auger Observatory

300

250

Two prototype layered water Cherenkov detectors were deployed at the Pierre Auger Observatory in Malargüe, Argentina in 2014 and have since been stably recording data.



The prototypes are modified Auger water Cherenkov detectors with a separation layer 80 cm from the bottom of the tank and a single additional PMT in the bottom layer.





2000

Bottom PMT Calibration



Conclusions and Outlook

Calibration of the bottom PMTs show stable functioning of the bottom layer of the detector. The muon hump of the top PMTs is swallowed by the electromagnetic contribution.

Outlook: Develop more advanced methods to extract the calibration constants of the top PMTs from the shape of the muon signals and coincidence calibration histograms with the bottom PMT.

References

[1] A. Letessier-Selvon et al., Nucl. Instrum. Meth. A **767** (2014).
[2] S. Kunwar et al., Nucl. Instrum. Meth. A **1050** (2023).

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